

Summary and Notes

SUMMARY

1. A field is a function that specifies a quantity in space. For example, $\mathbf{A}(x, y, z)$ is a vector field, whereas $V(x, y, z)$ is a scalar field.
2. A vector \mathbf{A} is uniquely specified by its magnitude and a unit vector along it, that is, $\mathbf{A} = A\mathbf{a}_A$.
3. Multiplying two vectors \mathbf{A} and \mathbf{B} results in either a scalar $\mathbf{A} \cdot \mathbf{B} = AB \cos \theta_{AB}$ or a vector $\mathbf{A} \times \mathbf{B} = AB \sin \theta_{AB} \mathbf{a}_n$. Multiplying three vectors \mathbf{A} , \mathbf{B} , and \mathbf{C} yields a scalar $\mathbf{A} \cdot (\mathbf{B} \times \mathbf{C})$ or a vector $\mathbf{A} \times (\mathbf{B} \times \mathbf{C})$.
4. The scalar projection (or component) of vector \mathbf{A} onto \mathbf{B} is $A_B = \mathbf{A} \cdot \mathbf{a}_B$, whereas vector projection of \mathbf{A} onto \mathbf{B} is $\mathbf{A}_B = A_B \mathbf{a}_B$.
5. The MATLAB commands `dot(A,B)` and `cross(A,B)` are used for dot and cross products, respectively.

SUMMARY

1. The three common coordinate systems we shall use throughout the text are the Cartesian (or rectangular), the circular cylindrical, and the spherical.
2. A point P is represented as $P(x, y, z)$, $P(\rho, \phi, z)$, and $P(r, \theta, \phi)$ in the Cartesian, cylindrical, and spherical systems, respectively. A vector field \mathbf{A} is represented as (A_x, A_y, A_z) or $A_x \mathbf{a}_x + A_y \mathbf{a}_y + A_z \mathbf{a}_z$ in the Cartesian system, as (A_ρ, A_ϕ, A_z) or $A_\rho \mathbf{a}_\rho + A_\phi \mathbf{a}_\phi + A_z \mathbf{a}_z$ in the cylindrical system, and as (A_r, A_θ, A_ϕ) or $A_r \mathbf{a}_r + A_\theta \mathbf{a}_\theta + A_\phi \mathbf{a}_\phi$ in the spherical system. It is preferable that mathematical operations (addition, subtraction, product, etc.) be performed in the same coordinate system. Thus, point and vector transformations should be performed whenever necessary. A summary of point and vector transformations is given in Table 2.1.
3. Fixing one space variable defines a surface; fixing two defines a line; fixing three defines a point.
4. A unit normal vector to surface $n = \text{constant}$ is $\pm \mathbf{a}_n$.

Notes:

- 1- Make a good sketch of the problem. A professional engineer should be able to express the problem with appropriate engineering drawing.
- 2- From the sketch, try to use symmetry to simplify the analysis, whenever applicable.
- 3- An example of scalar fields and vector fields in Electromagnetics are:
Electric Potential V in Volt (V)
Electric field intensity \mathbf{E} in V/m
We are going to investigate these fields in details in our course.
- 4- For a point charge Q in C, located at the origin, we have:

$$\mathbf{E} = \frac{Q}{4\pi\epsilon_0 r^2} \mathbf{a}_r$$

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$$V = \frac{A}{r} + Const$$

Where $A \propto Q$

5- For an infinite line on the z-axis with uniform charge density ρ_L C/m, we have:

$$\mathbf{E} = \frac{B}{\rho} \mathbf{a}_\rho$$

$$V = -B \ln(\rho) + Const$$

Where $B \propto \rho_L$

Thinking Questions:

- What are the units of constants A and B above?
- Can you guess the relationship between V and E?
- What should make the surfaces on which V is constant for point charge and infinite line charge cases?

Solved Examples:

Example 1:

Consider the field $\vec{E} = \frac{xy}{3} \vec{a}_y$. Sketch the field components at $P(x=3, y=4, z=5)$ in x-y and ρ -z planes. Show on the figure the components of \mathbf{E} in cartesian, cylindrical and spherical coordinates.

Solution:

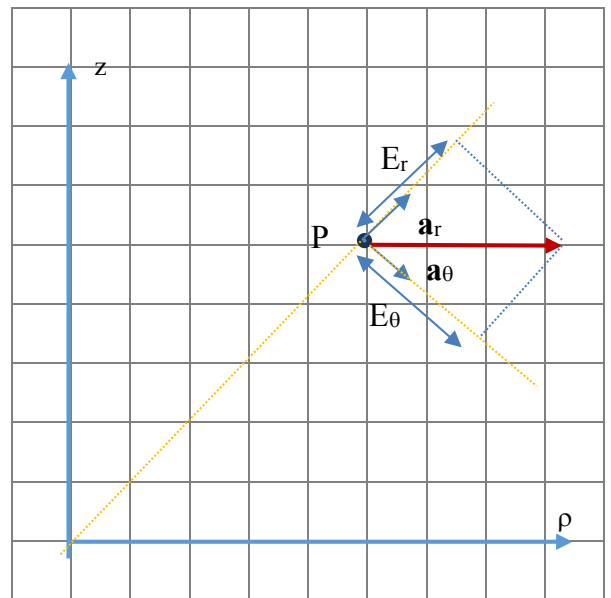
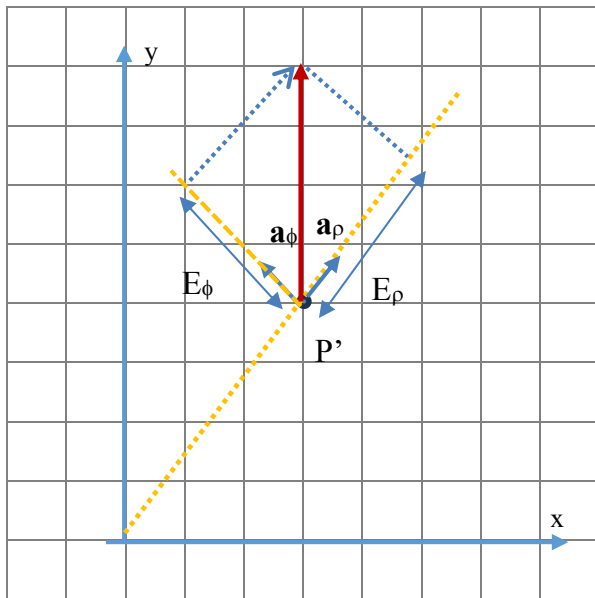
$$\vec{E}_P = \frac{3 \times 4}{3} \vec{a}_y = 4 \vec{a}_y$$

Starting from project of P on x-y plane, sketch a vector of magnitude 4 in \vec{a}_y direction.

Project \mathbf{E} on \vec{a}_ρ and \vec{a}_ϕ directions.

Measure E_ρ components and sketch it starting from P on ρ -z plane.

Project E_ρ on \vec{a}_r and \vec{a}_θ directions.

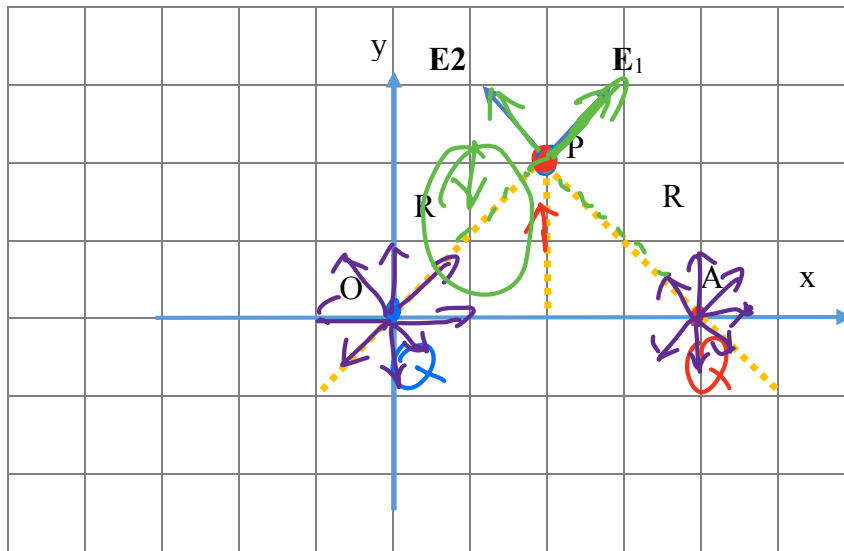


Example 2:

Q^+ positive

Using the figure below, find:

- If point charge Q is located at the origin, what is V and \mathbf{E} ?
- If there are two charges $Q_1=Q$ at O and $Q_2=Q$ at A , find V and \mathbf{E} at $P(2,2,0)$.



- One charge is located at the origin.
From Note 4 above:

$$\mathbf{E} = \frac{A}{r^2} \mathbf{a}_r$$

$$V = \frac{A}{r} + \text{Const}$$

Where $A \propto Q$

- We can make use of symmetry in this case. \mathbf{E} has only \mathbf{a}_y component.

$$R = 2\sqrt{2}$$

$$\mathbf{E} = \mathbf{E}_1 + \mathbf{E}_2$$

$$\mathbf{E}_1 = \frac{A}{8} \frac{(1,1,0)}{\sqrt{2}}$$

$$\mathbf{E}_2 = \frac{A}{8} \frac{(-1,1,0)}{\sqrt{2}}$$

$$\mathbf{E}_P = \frac{\sqrt{2}A}{8} \mathbf{a}_y \text{ V/m}$$

$$V_P = V_1 + V_2 = 2V_1$$

$$V_P = 2 \frac{A}{2\sqrt{2}} + \text{Const}$$

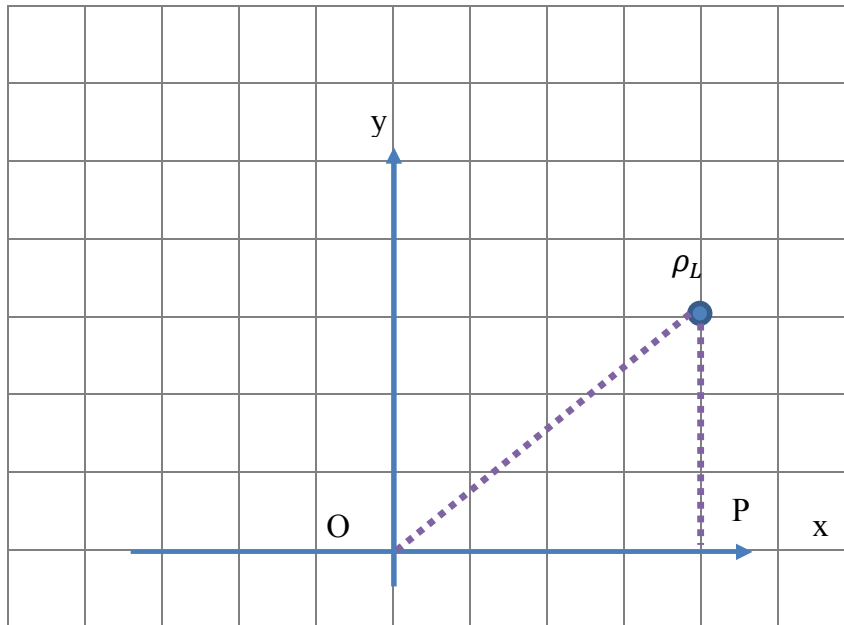
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Example 3:

In the figure below, an infinite line with uniform charge density ρ_L is located at $x=4$ and $y=3$. Find:

- i. \mathbf{E} at O
- ii. V at P



Solution:

From Note 5

$$\mathbf{E} = \frac{B}{R} \mathbf{a}_R$$

For field at O, $R=5$ and $\mathbf{a}_R = \frac{(-4, -3, 0)}{5}$

$$\mathbf{E}_O = \frac{B(-4, -3, 0)}{25}$$

For V at P

$$V_P = -B \ln(3) + \text{Const}$$

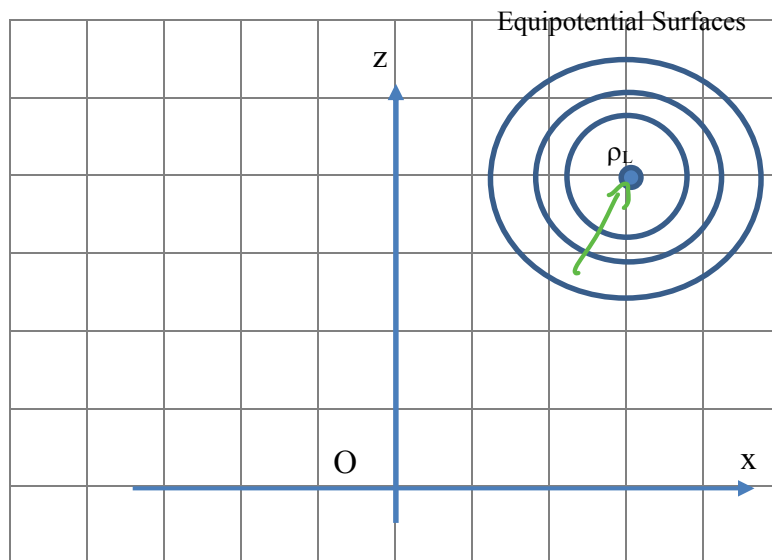
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Example 4:

Line $x=3, z=4$ carries uniform charge. Identify the equipotential surfaces.

Remember: without a correct sketch, your answer has no engineering value.



Equipotential surfaces are cylinders with axis at $x=3$ and $z=4$

Example 5:

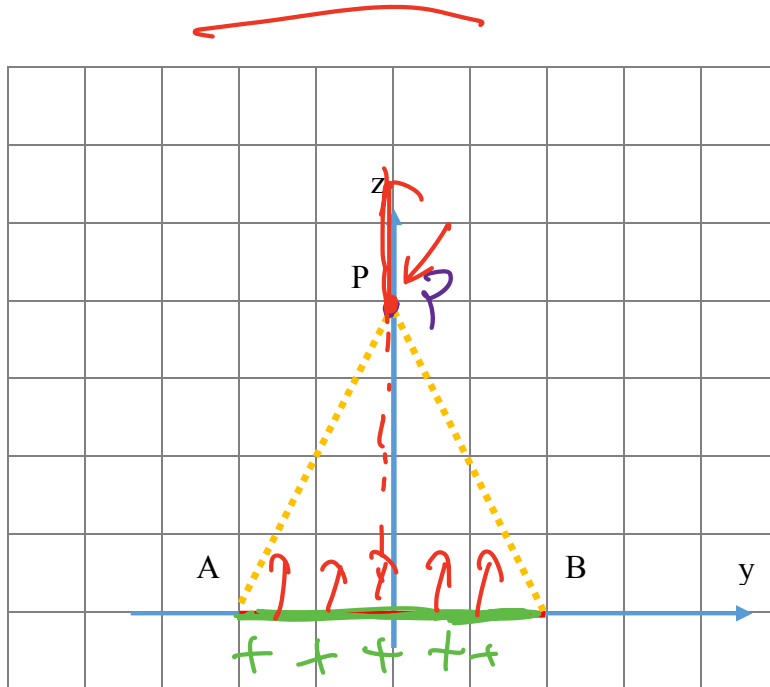
A line charge with uniform charge density exists between points A(0, -1, 0) and B(0, 1, 0). Find the direction of \mathbf{E} at P(0,0,2).

Solution:

First sketch the problem.

Remember: without correct sketch, your answer has no engineering value.

From symmetry \mathbf{E} should be in \mathbf{a}_z direction



\mathbf{E} at \mathbf{a}_z direction
?

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$$\rho = \sqrt{x^2 + y^2}$$

Example 5:

Given that $V = 10\rho^2 \sin \phi$ V, find V at $P(x=3, y=4, z=5)$

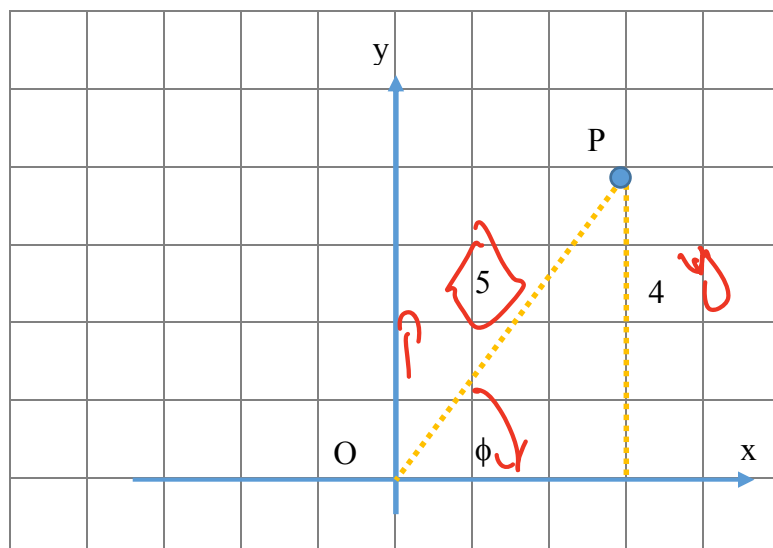
$$\rho = ?$$

$$\phi = ?$$

Solution

Make a sketch. From figure, $\rho=5$ and $\sin(\phi) = 4/5$

$$V = 10 \times 25 \times \frac{4}{5} = 200 \text{ V}$$



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Problems:

Vector Algebra:

Q1) Correct the following statements:

- $\vec{A} \times \vec{A} = A^2$
- $\vec{A} \cdot (\vec{B} \cdot \vec{C}) = \vec{B} \cdot (\vec{C} \cdot \vec{A})$

Q2) Find the vector component of $\vec{A} = 6\vec{a}_x + 2\vec{a}_y - 3\vec{a}_z$ along $\vec{B} = 3\vec{a}_x - \vec{a}_y$

Q3) Find the shortest distance from point $P(0,0,3)$ to the line that passes through origin and $A(2,2,2)$

Coordinate Systems:

Q1) Describe the following geometries:

- $\theta = 30^\circ$
- $r = 3$ & $\theta = 30^\circ$
- $\phi = \pi/2$
- $\rho = 5$ & $\phi = \pi/2$
- $x = -10$
- $x = -10$ & $y = 3$

Q2) What is the unit normal vector to the cone: $\theta = 30^\circ$?

Q3) Sketch the field $\vec{E} = xy\vec{a}_x + 2z\vec{a}_y + 2y\vec{a}_z$ at point $P(x=0, y=1, z=1)$ in x-y and ρ -z planes. Hence, express \vec{E}_P in cylindrical and spherical coordinates.

Q4) Sketch the field $\vec{E} = \rho z\vec{a}_\rho + \rho^2\vec{a}_z$ at point $P(x=0, y=-1, z=0)$ in x-y and ρ -z planes. Hence, express \vec{E}_P in Cartesian and spherical coordinates.

E and V Fields (See Notes 4 and 5 above)

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Q1) A charge Q is located at $P(2, 3, 0)$.

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- Identify the equipotential surfaces.
- Find direction of \mathbf{E} at $A(2, 0, 0)$ and $B(-, 3, 0)$.

Q2) An infinite line charge is located at $x=4$ and $z=3$. Find \mathbf{E} and V at $A(2, 0, 3)$

Q3) Three charges of magnitude Q are located at $A(-1, 0, 0)$, $B(1, 0, 0)$ and $C(3, 0, 0)$.

Find \mathbf{E} and V at $P(-3, 0, 0)$.

Q4) Given that $V = \frac{10}{r} \sin(\theta) \cos \phi$ V, find V at $P(x=3, y=4, z=5)$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$V =$$

Vector Algebra:

Q1) Correct the following statements:

- i. $\vec{A} \times \vec{A} = A^2$
 ii. $\vec{A} \cdot (\vec{B} \cdot \vec{C}) = \vec{B} \cdot (\vec{C} \cdot \vec{A})$

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Q2) Find the vector component of $\vec{A} = 6\vec{a}_x + 2\vec{a}_y - 3\vec{a}_z$ along $\vec{B} = 3\vec{a}_x - \vec{a}_y$

Q3) Find the shortest distance from point P(0,0,3) to the line that passes through origin and A(2,2,2)

Q1)

i) $\vec{A} \times \vec{A} = 0$
 $\vec{A} \cdot \vec{A} = A^2$

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ii)

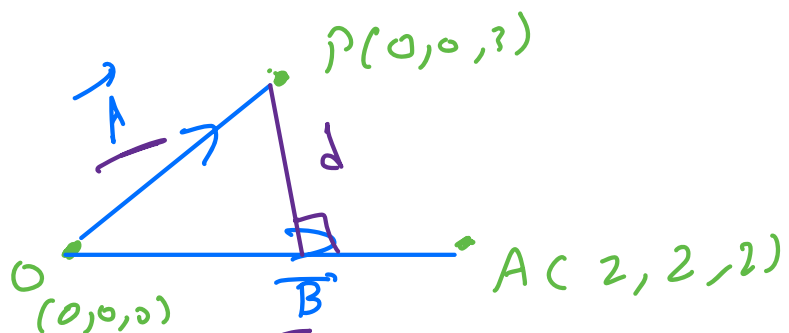
$$\vec{A} \cdot (\vec{B} \times \vec{C}) = \vec{B} \cdot (\vec{C} \times \vec{A})$$

Q2)

$$\text{Comp}_{AB} = \frac{\vec{A} \cdot \vec{B}}{|\vec{B}|} = \frac{18 - 2 + 0}{\sqrt{9+1}} \vec{u}_B$$

$$= \frac{16}{\sqrt{10}} \vec{u}_B = \frac{16}{\sqrt{10}} \frac{3\vec{a}_x - \vec{a}_y}{\sqrt{9+1}}$$

Q3)



$$d = \frac{|\vec{A} \times \vec{B}|}{|\vec{B}|} = \langle -6, 6, 0 \rangle$$

$\vec{A} \times \vec{B}$

$$\begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ 0 & 0 & 3 \\ 2 & 2 & 2 \end{vmatrix}$$

$$= \langle -6, 6, 0 \rangle$$

$$= -6 \hat{a}_x + 6 \hat{a}_y$$

$$= \frac{6\sqrt{2}}{\sqrt{2}} \left[-\hat{a}_x + \hat{a}_y \right]$$

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Coordinate Systems:

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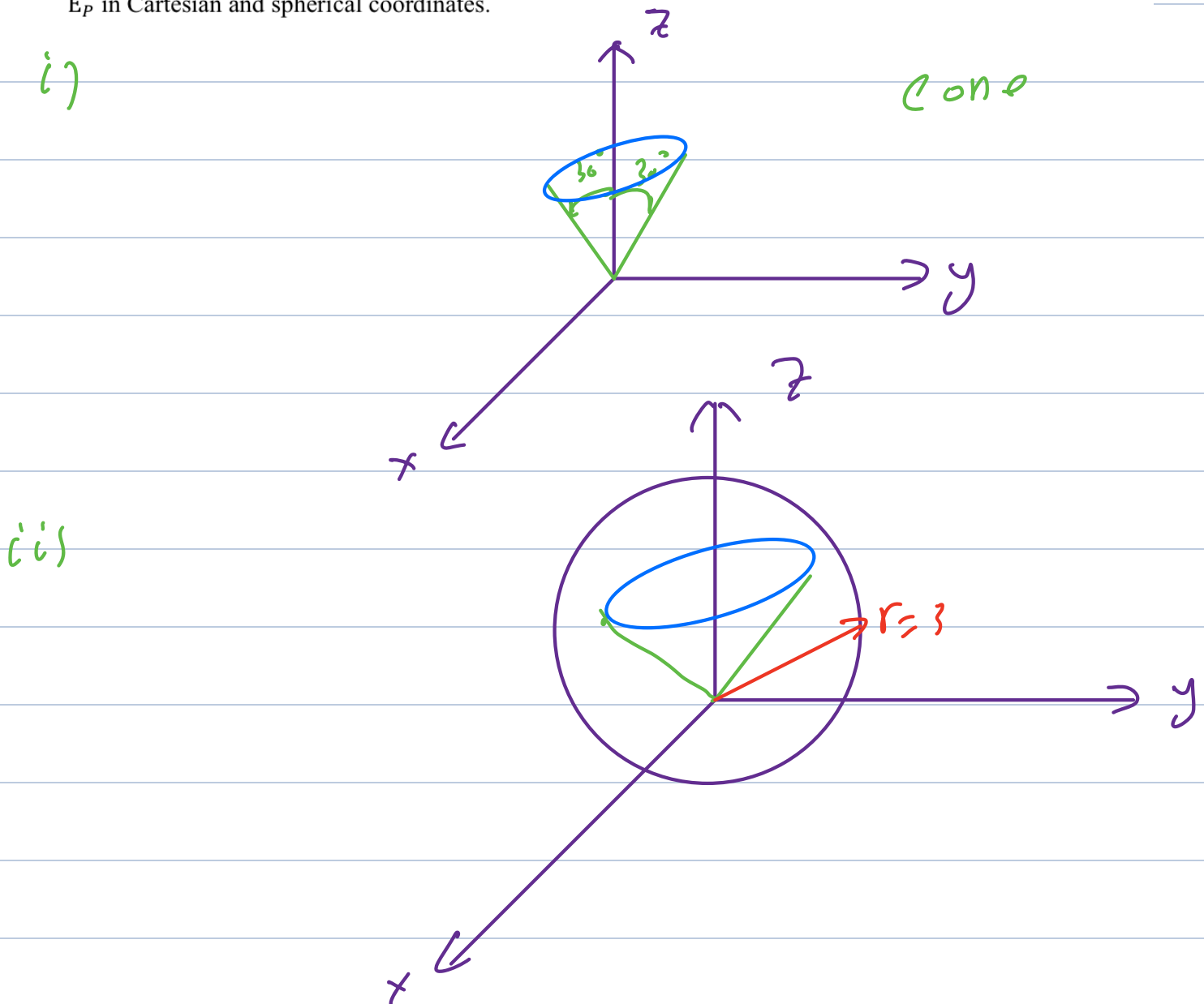
Q1) Describe the following geometries:

- i. $\theta = 30^\circ$
- ii. $r = 3$ & $\theta = 30^\circ$
- iii. $\phi = \pi/2$
- iv. $\rho = 5$ & $\phi = \pi/2$
- v. $x = -10$
- vi. $x = -10$ & $y = 3$

Q2) What is the unit normal vector to the cone: $\theta = 30^\circ$?

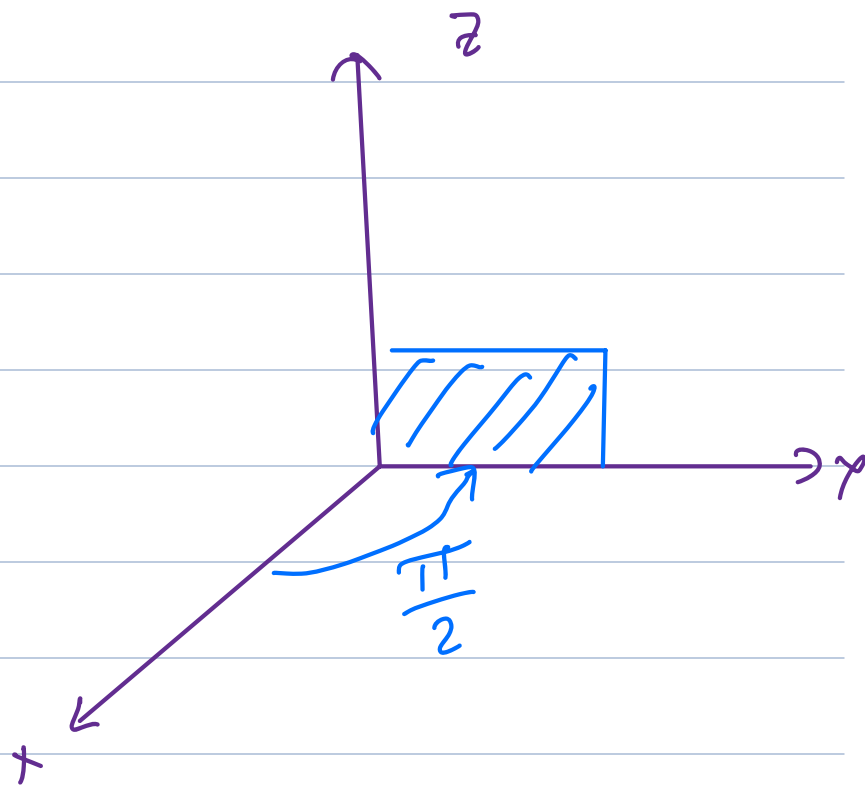
Q3) Sketch the field $\vec{E} = xy \vec{a}_x + 2z \vec{a}_y + 2y \vec{a}_z$ at point $P(x=0, y=1, z=1)$ in x-y and ρ -z planes. Hence, express \vec{E}_P in cylindrical and spherical coordinates.

Q4) Sketch the field $\vec{E} = \rho z \vec{a}_\rho + \rho^2 \vec{a}_z$ at point $P(x=0, y=-1, z=0)$ in x-y and ρ -z planes. Hence, express \vec{E}_P in Cartesian and spherical coordinates.



(ii)

plane
 $\phi = \frac{\pi}{2}$



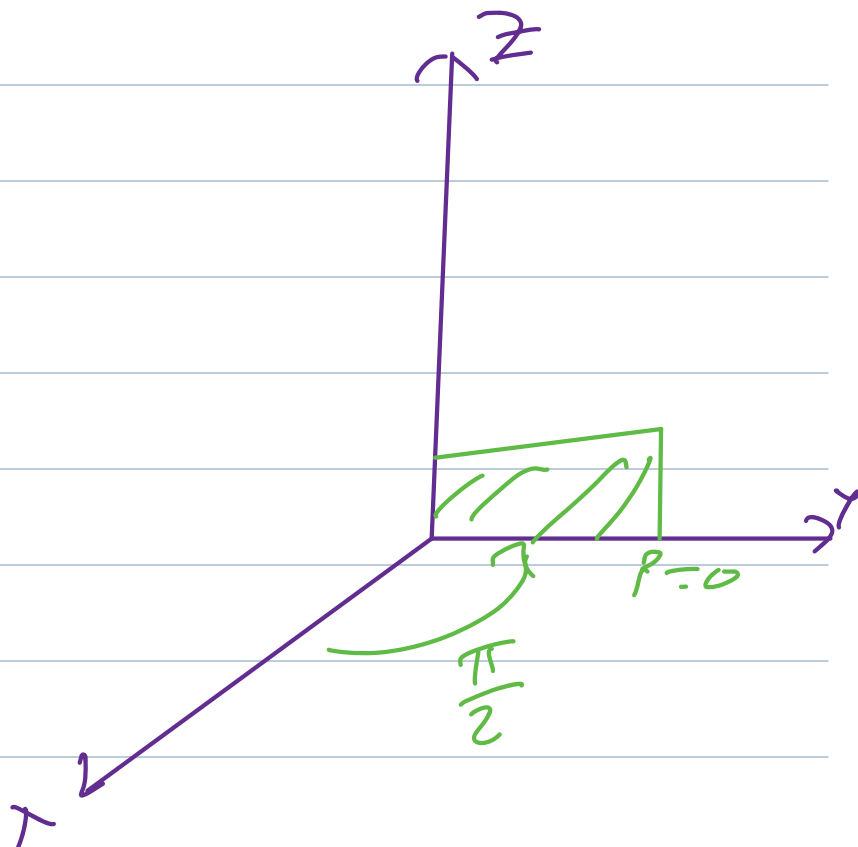
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(iv)

plane

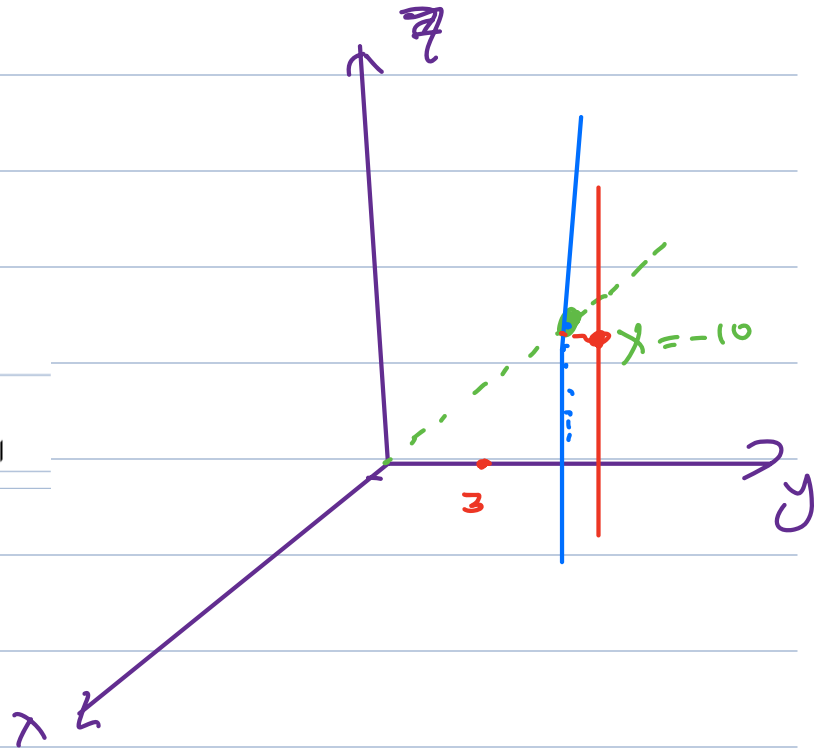
$p = 5$ $\phi = \frac{\pi}{2}$



✓

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Q2) What is the unit normal vector to the cone: $\theta = 30^\circ$?

Q3) Sketch the field $\vec{E} = xy \vec{a}_x + 2z \vec{a}_y + 2y \vec{a}_z$ at point $P(x=0, y=1, z=1)$ in x-y and ρ -z planes. Hence, express \vec{E}_P in cylindrical and spherical coordinates.

Q4) Sketch the field $\vec{E} = \rho z \vec{a}_\rho + \rho^2 \vec{a}_z$ at point $P(x=0, y=-1, z=0)$ in x-y and ρ -z planes. Hence, express \vec{E}_P in Cartesian and spherical coordinates.

Q2

(r, θ, ϕ)

$$\vec{N} = 1 \hat{a}_r + 1 \hat{a}_\theta$$

$$\vec{u}_N = \frac{\vec{N}}{|\vec{N}|} = \frac{1 \hat{a}_r + 1 \hat{a}_\theta}{\sqrt{2}}$$

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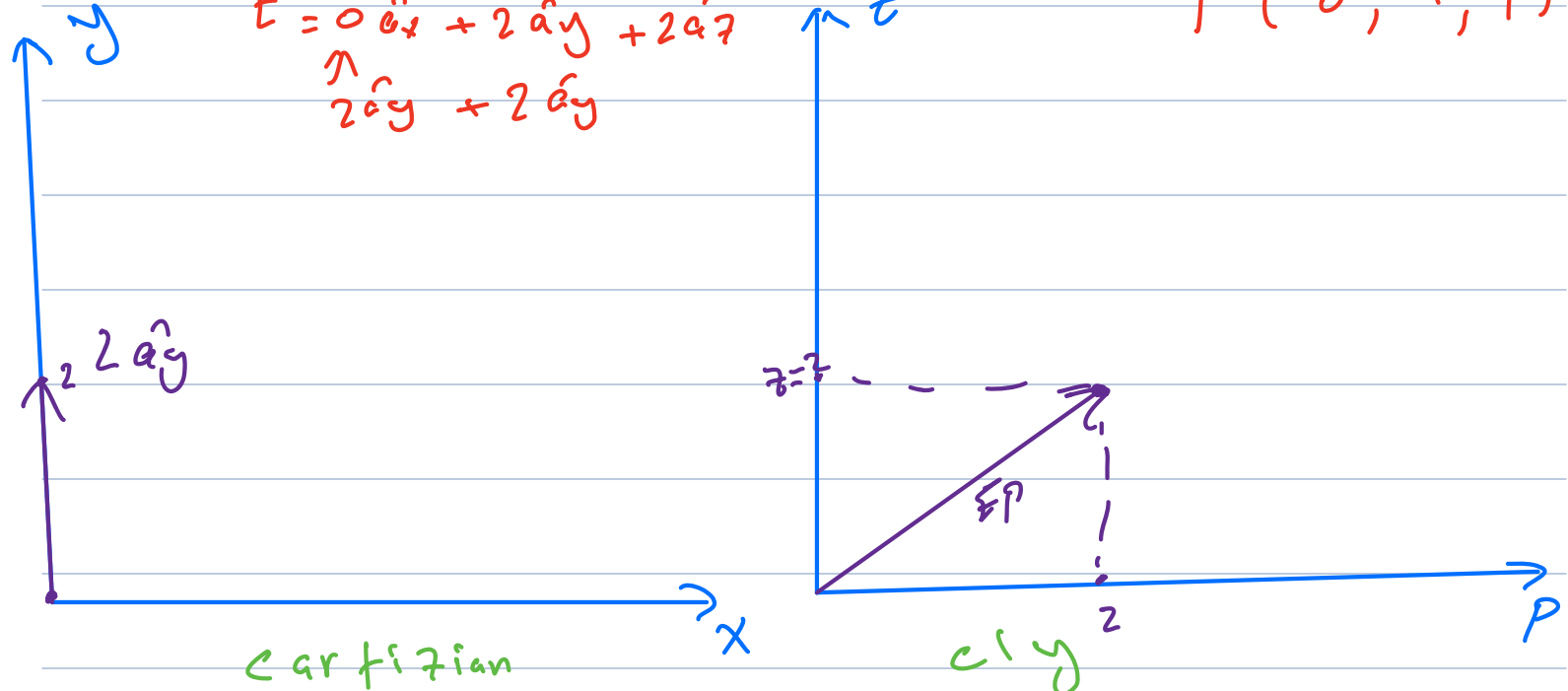
$$= \frac{1}{\sqrt{2}} \hat{a}_r + \frac{1}{\sqrt{2}} \hat{a}_\theta$$

Q2

$$\vec{E} = xy \hat{a}_x + 2z \hat{a}_y + 2y \hat{a}_z$$

$$\vec{E} = 0 \hat{a}_x + 2 \hat{a}_y + 2 \hat{a}_z$$

$P(0, 1, 1)$



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 $\xleftarrow{\quad}$

$$p(0, 1, 1)$$

$$\phi = \tan^{-1} \frac{p}{x}$$

$$= \tan^{-1} \frac{2}{0}$$

$$= 90^\circ$$

	A_p	A_ϕ	A_z
A_x	$\cos \phi$	$\sin \phi$	0
A_y	$\sin \phi$	$\cos \phi$	0
A_z	0	0	1

↓

$$A_p = A_x \cos \phi + A_y \sin \phi + 0 A_z$$

$$A_x = \cos \phi A_p + A_\phi \sin \phi + 0 A_z$$

$$\vec{E} = 0 \hat{a}_x + 2 \hat{a}_y + 2 \hat{a}_z$$

$$A_p = A_x \cos \phi + A_y \sin \phi + \boxed{0 A_z}$$

$$A_\phi = A_x \sin \phi + A_y \cos \phi + 0 A_z$$

$$A_z = A_z$$

$$\phi = 90^\circ$$

$$A_p = 2 \sin 90^\circ = 2$$

$$A_\phi = 0$$

$$A_z = 2$$

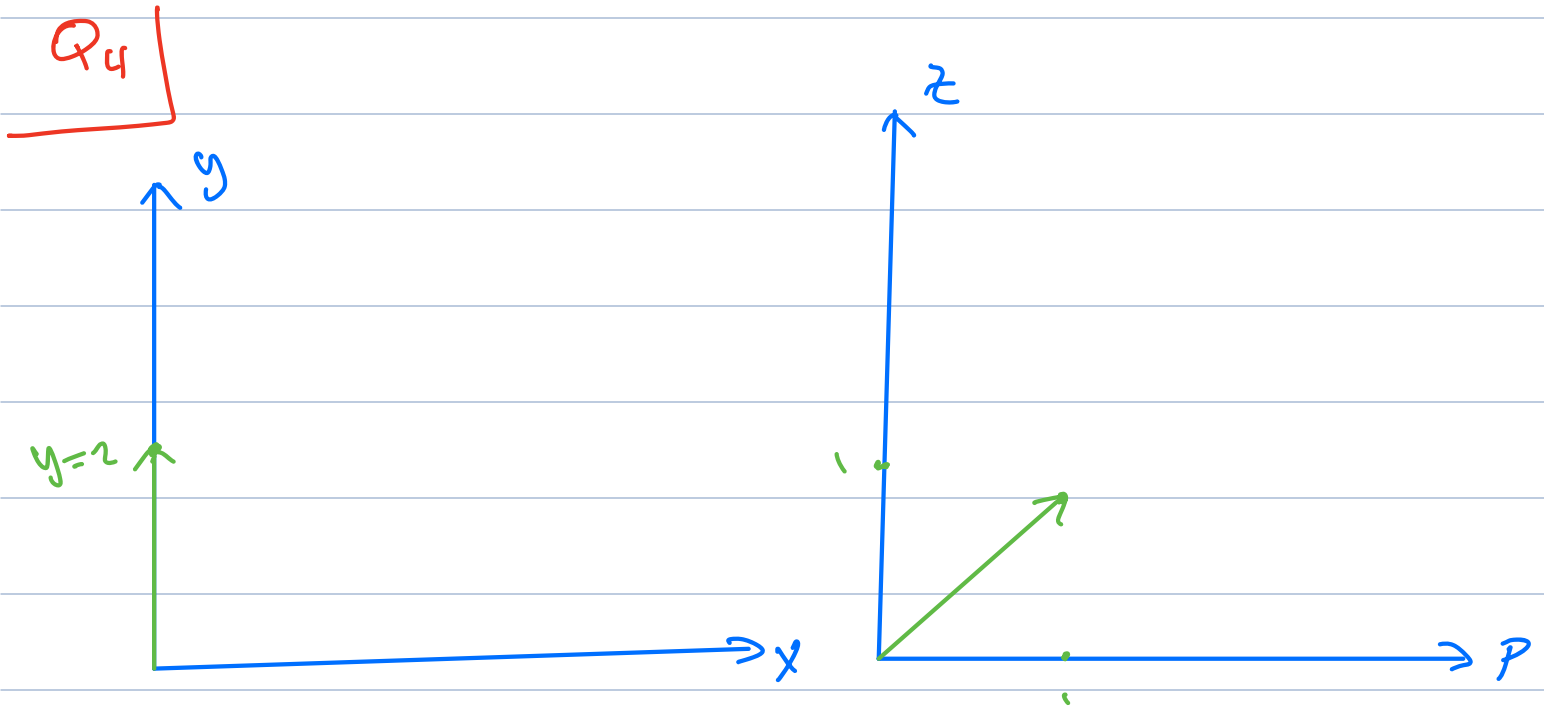
$$\vec{E}_p = 2 \hat{a}_p + 0 \hat{a}_\phi + 2 \hat{a}_z$$

$$A_r = \frac{4}{\sqrt{2}}$$

$$A_\theta = 0$$

$$A_\phi = 0$$

$$\vec{E} = \frac{4}{\sqrt{2}} \hat{a}_r + 0 \hat{a}_\theta + 0 \hat{a}_\phi$$



cart $\vec{E} = 0 \hat{a}_x + 1 \hat{a}_y + \hat{a}_z$

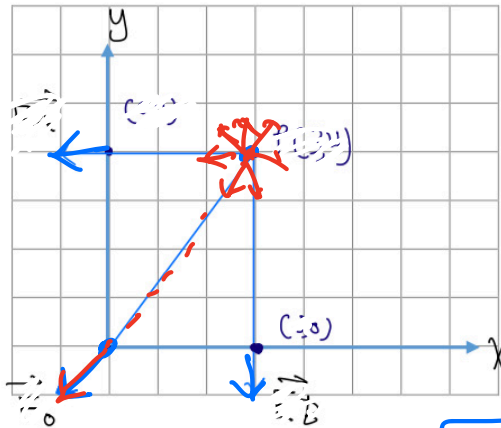
cly $\vec{E} = 1 \hat{e}_p + 0 \hat{e}_q + 1 \hat{a}_z$

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الاسم: _____ الرقم: _____ رقم التحضير: _____

Q1) A point positive charge Q is located at $P(3, 4, 0)$. Makeup a sketch to show the direction of \mathbf{E} at: Origin O , $A(0, 4, 0)$ and $B(3, 0, 0)$.



Q2) Consider the field $\vec{E} = -\frac{xy^2}{18} \vec{a}_y$. Sketch the field components at $P(x=4, y=3, z=5)$ in x-y and p-z planes. From the graph measure the following components:

$$E_x = 0$$

$$E_\rho = -2.8$$

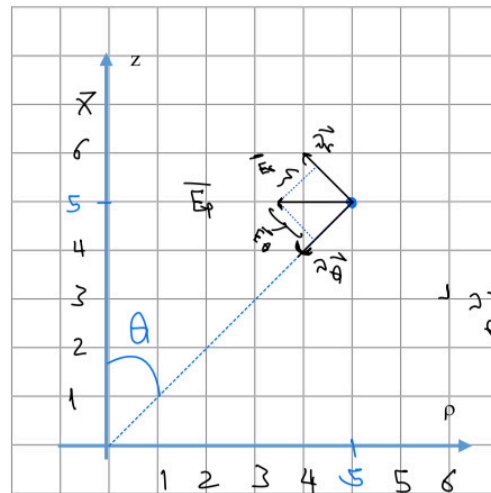
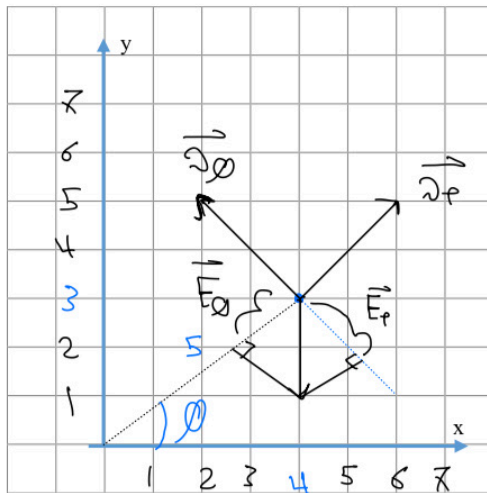
$$E_y = -2$$

$$E_\phi = -2.8$$

$$E_z = 0$$

$$E_r = -2.5$$

$$E_\theta = -2.6$$



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$$\vec{E} = \frac{x y^2}{18} a_{\hat{y}}$$

$$(4, 3, 5)$$

$$\vec{E} = \underline{0} a_{\hat{x}} + \frac{x y^2}{18} a_{\hat{y}} + 0 a_{\hat{z}}$$

$$\vec{E}_x = 0, \quad \vec{E}_z = 0, \quad \vec{E}_y = \frac{4 \times 3^2}{18}$$

$$\vec{E}_{\text{clg}} = \vec{E}_p + \vec{E}_\phi + \vec{E}_z$$

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